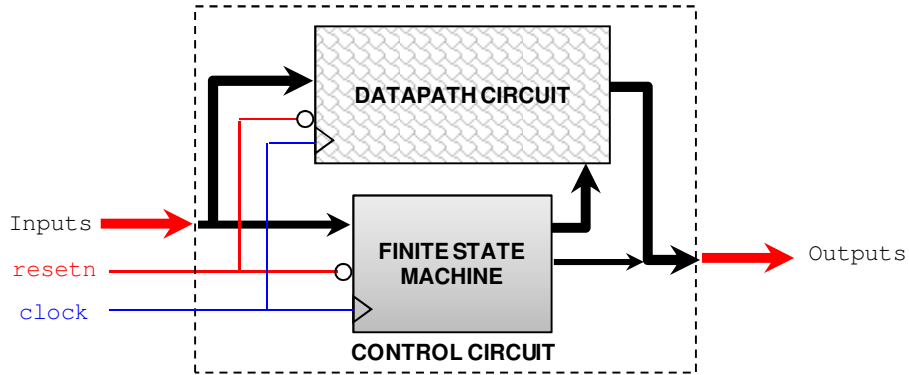


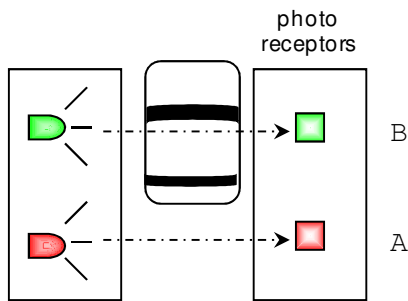
# Notes - Chapter 9

## COMPLEX FINITE STATE MACHINES

### Digital System Model: FSM + Datapath Circuit



### EXAMPLE: CAR LOT COUNTER



If A = 1 → No light received (car obstructing LED A)  
If B = 1 → No light received (car obstructing LED B)

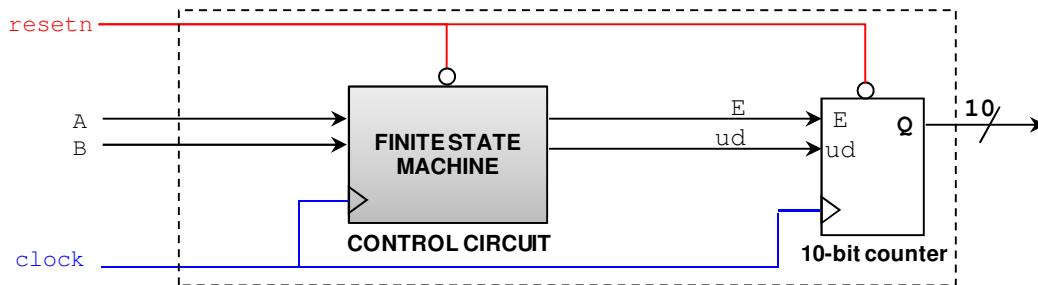
If car enters the lot, the following sequence (A|B) must be followed:

00 → 10 → 11 → 01 → 00

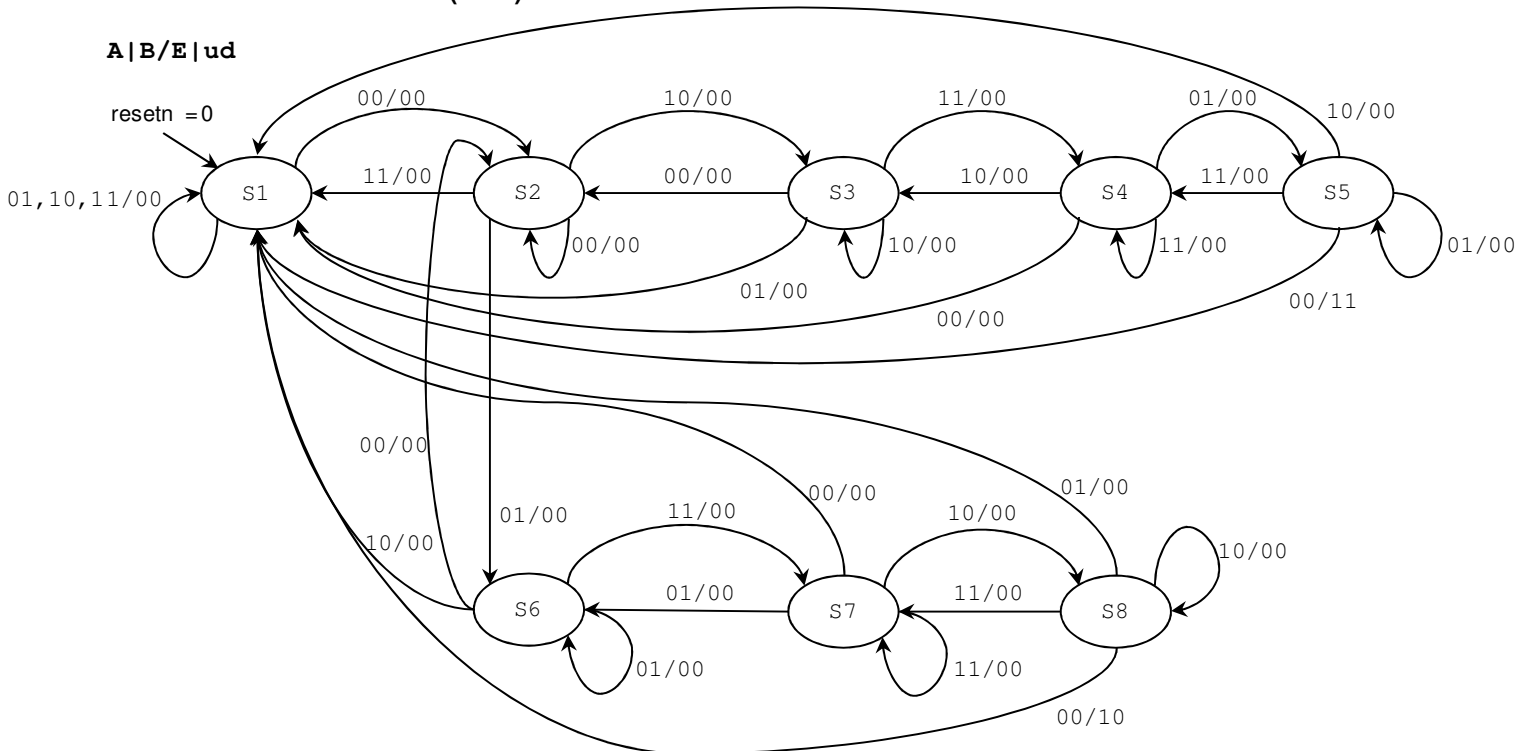
If car leaves the lot, the following sequence (A|B) must be followed:

00 → 01 → 11 → 10 → 00

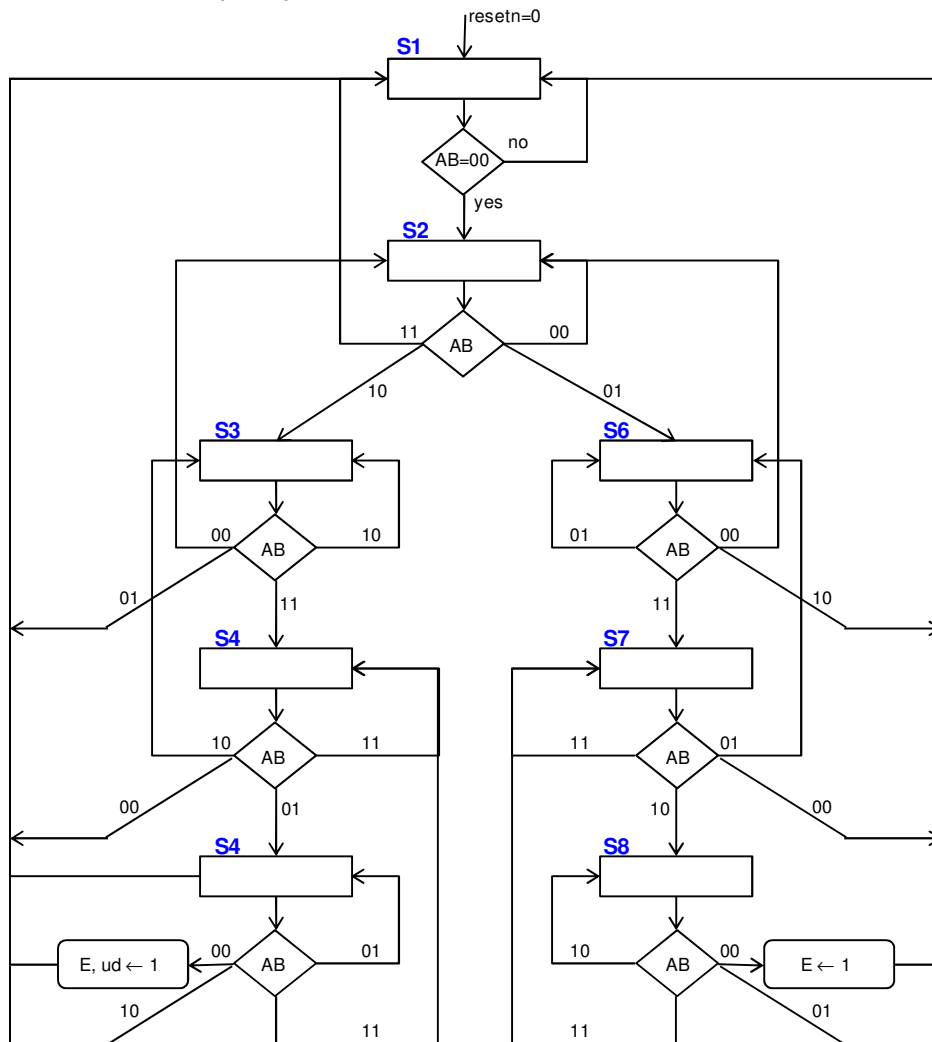
- **FSM + Datapath circuit:** Usually, when 'resetn' (asynchronous clear), and 'clock' are not drawn, they are implied.



Finite State Machine (FSM):



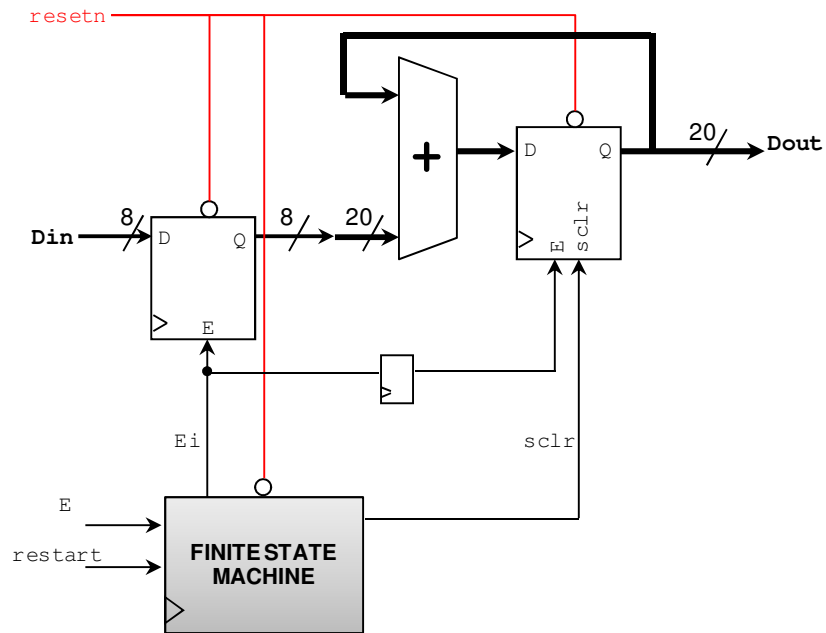
Algorithmic State Machine (ASM) chart:



EXAMPLE: ACCUMULATOR

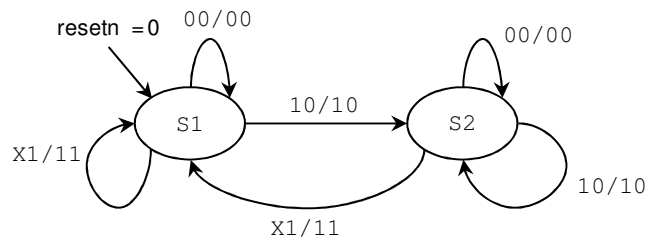
FSM + Datapath circuit:

sclr: Synchronous clear. If E = '1' and sclr = '1', then the output bits of the registers are set to zero.

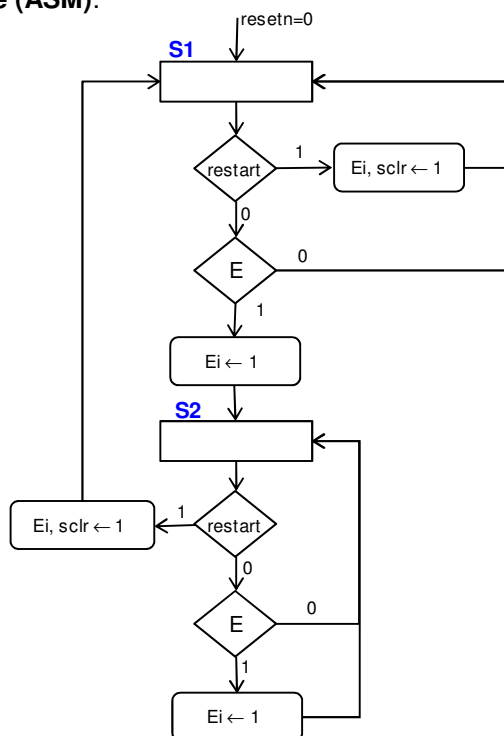


Finite State Machine (FSM):

E | restart / Ei | sclr

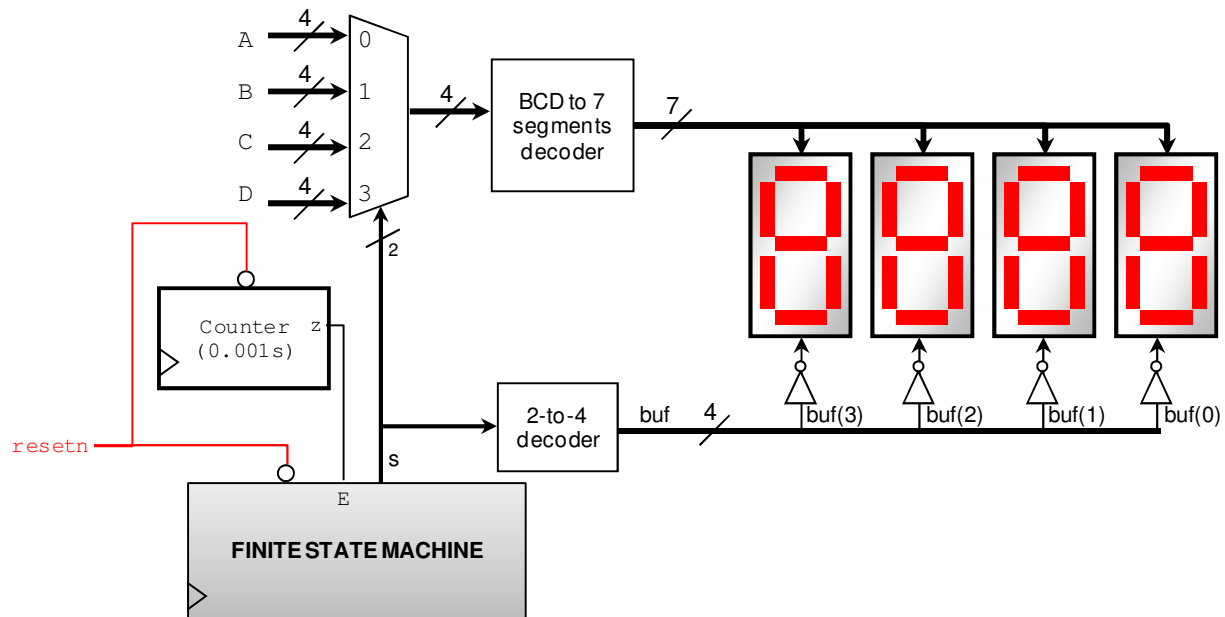


Algorithmic State Machine (ASM):

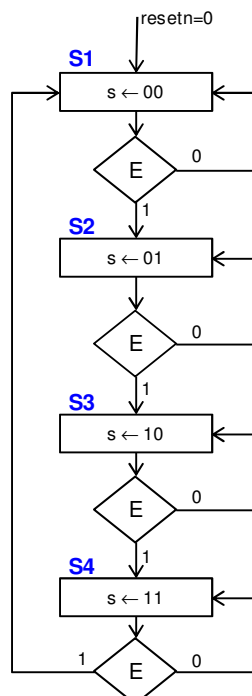


### EXAMPLE: 7-SEGMENT SERIALIZER

- **FSM + Datapath circuit:**
- There are four 7-segment displays on the NEXYS3 board. However, only one can be used at a time.
- If we want to display four digits (inputs A, B, C, D), we can design a serializer that will only show one digit at a time on the 7-segment displays.
- Since only one 7-segment display can be used at a time, we need to serialize the four BCD outputs. In order for each digit to appear bright and continuously illuminated, each digit is illuminated for 1 ms every 4 ms (i.e. a digit is un-illuminated for 3 ms and illuminated for 1 ms). This is taken care of by feeding the output 'z' of the counter to 0.001 s to the enable input of the FSM. This way, state transitions only occur each 0.001 s.
- Also, the enable signals for the 4 7-segment displays on the NEXYS are active low.



- **Algorithmic State Machine (ASM) chart:** This is a Moore-type FSM.



## EXAMPLE: BIT-COUNTING CIRCUIT

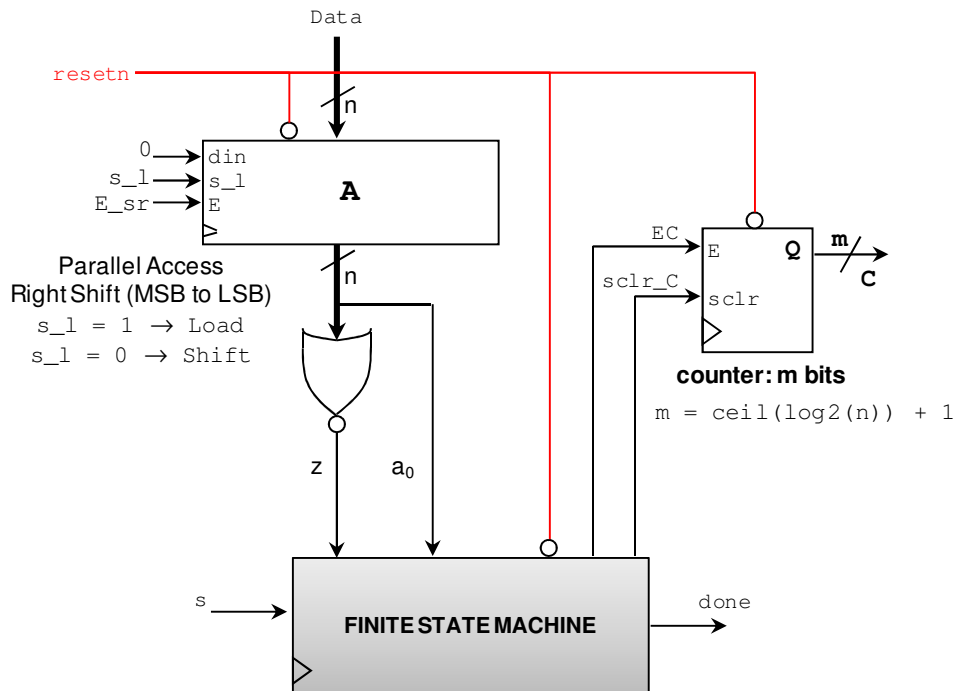
- Sequential Algorithm:**

```

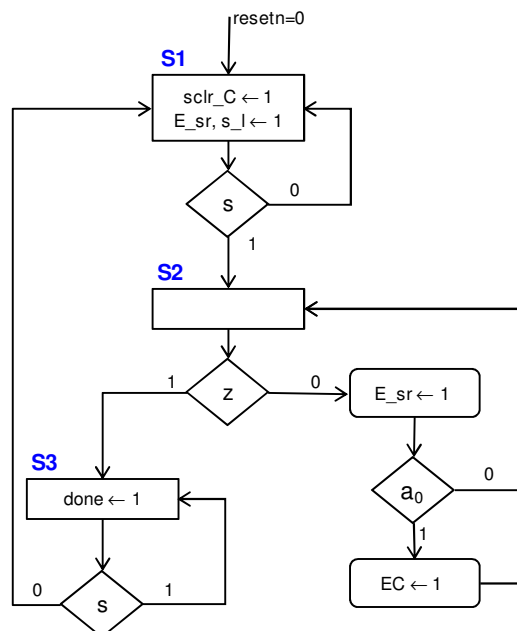
C ← 0
while A ≠ 0
    if a0 = 1 then
        C ← C + 1
    end if
    right shift A
end while
    
```

- FSM + Datapath circuit:**

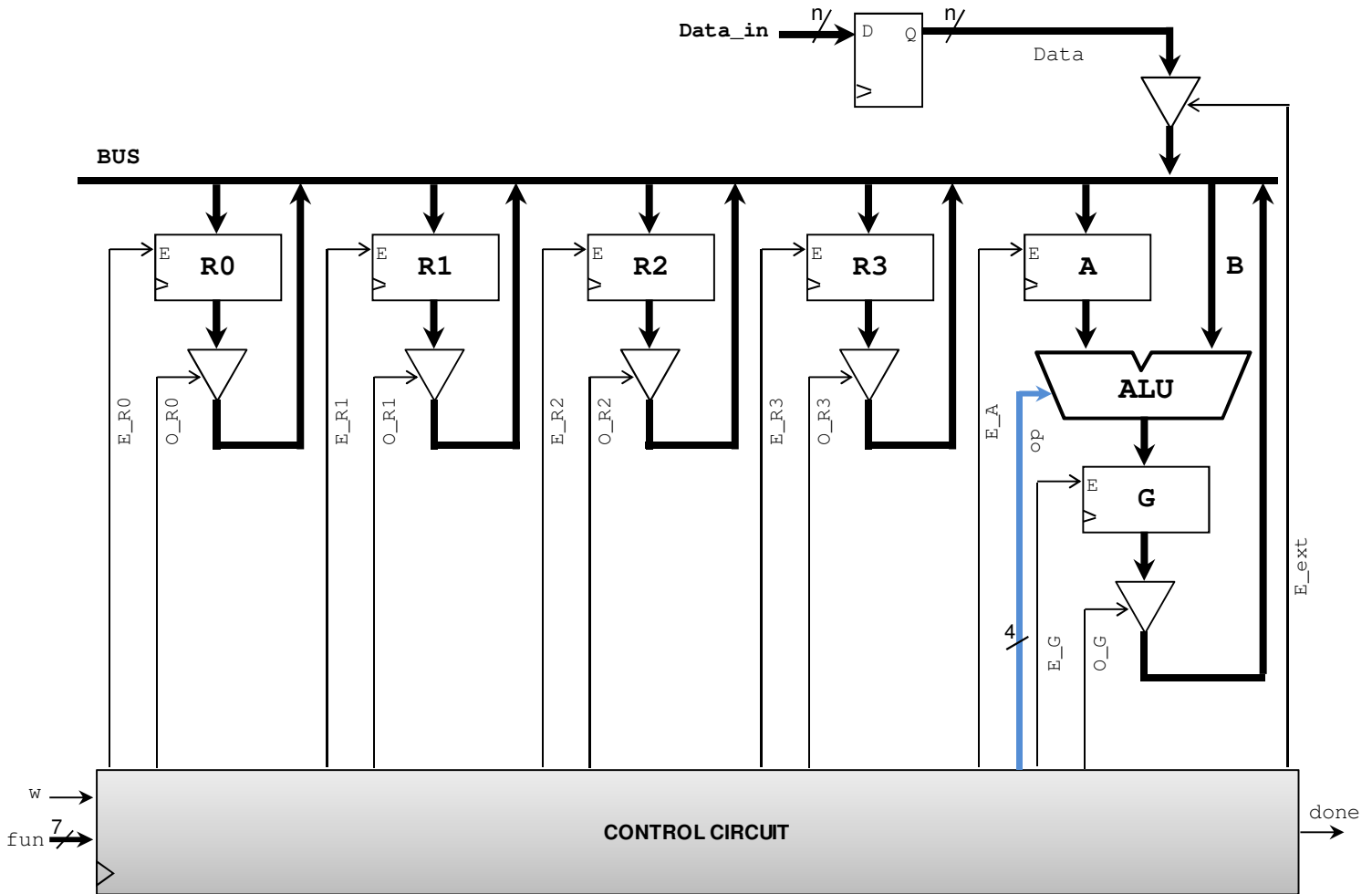
sclr: Synchronous clear. In this case, if sclr = '1', the count is initialized to zero. Note that here, we do not need EC to be 1



- Algorithmic State Machine (ASM) chart:**



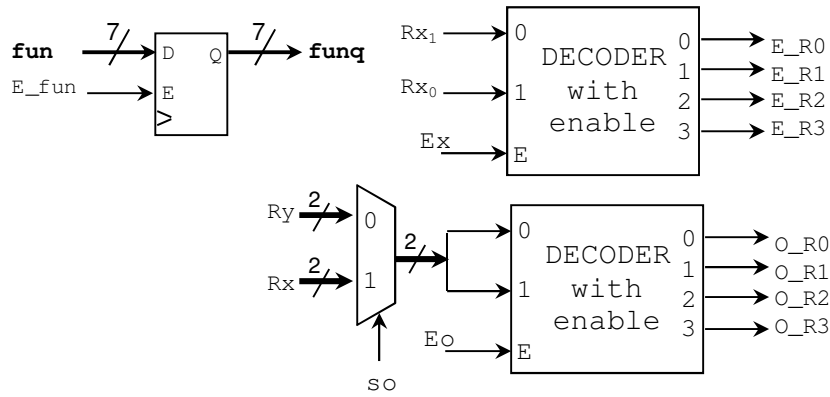
EXAMPLE: SIMPLE PROCESSOR



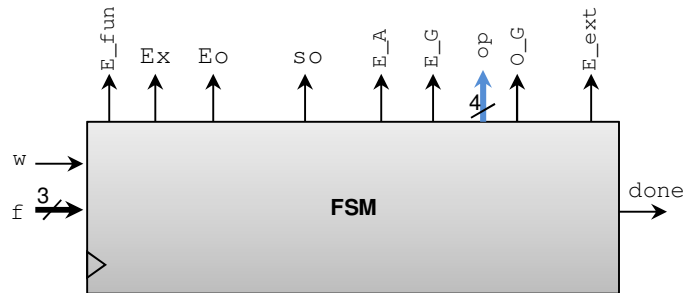
- Operation: Every time  $w = '1'$ , we grab the instruction from  $fun$  and execute it:
- $funq = |f_2|f_1|f_0|Rx_1|Rx_0|$

<b>f</b>	<b>Operation</b>	<b>Function</b>
000	Load $R_x$ , Data	$R_x \leftarrow Data$
001	Move $R_x$ , $R_y$	$R_x \leftarrow R_y$
010	Add $R_x$ , $R_y$	$R_x \leftarrow R_x + R_y$
011	Sub $R_x$ , $R_y$	$R_x \leftarrow R_x - R_y$
100	Not $R_x$	$R_x \leftarrow NOT (R_x)$
101	And $R_x$ , $R_y$	$R_x \leftarrow R_x AND R_y$
110	Or $R_x$ , $R_y$	$R_x \leftarrow R_x OR R_y$
111	Xor $R_x$ , $R_y$	$R_x \leftarrow R_x XOR R_y$

Control Circuit:



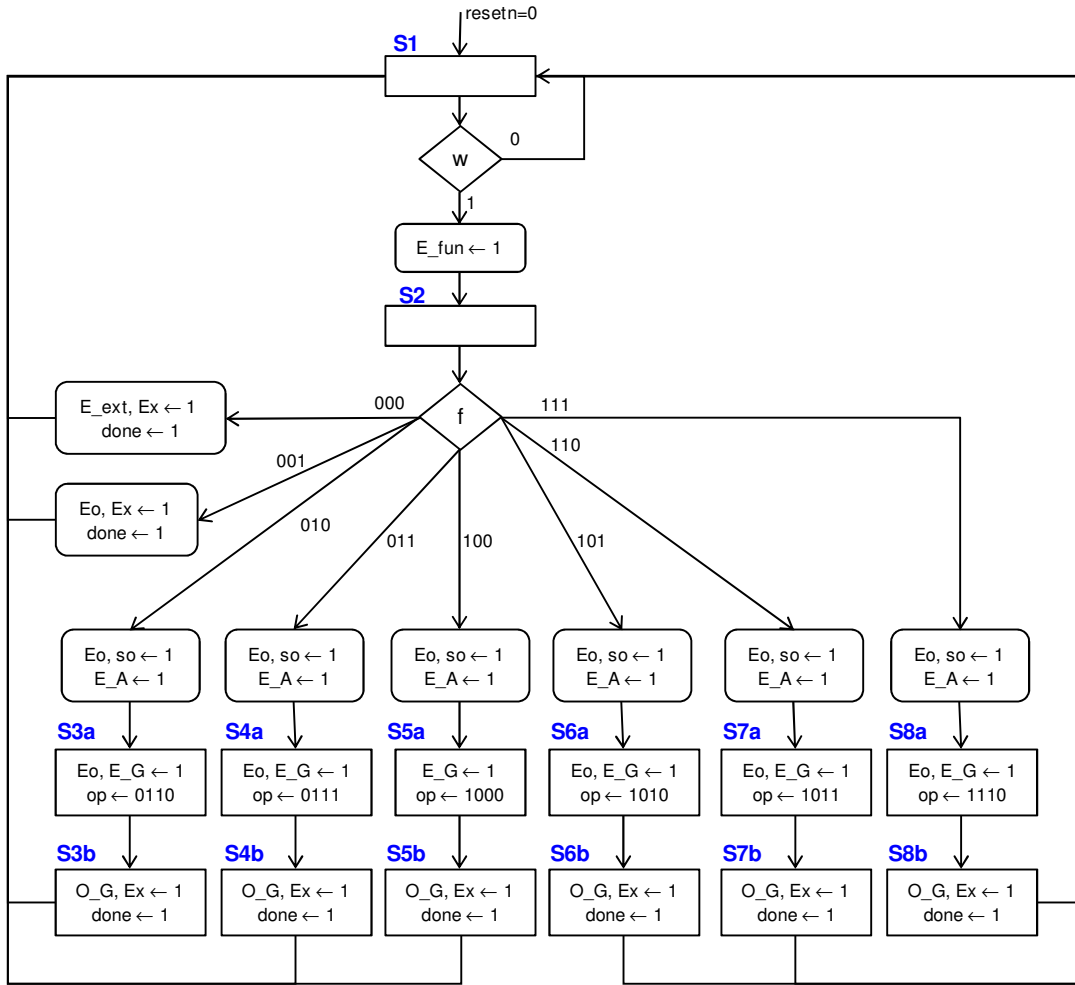
$$\text{func} = |f_2|f_1|f_0|Ry_1|Ry_0|Rx_1|Rx_0|$$



Arithmetic-Logic Unit (ALU):

op	Operation	Function	Unit
0000	y <= A	Transfer 'A'	Arithmetic
0001	y <= A + 1	Increment 'A'	
0010	y <= A - 1	Decrement 'A'	
0011	y <= B	Transfer 'B'	
0100	y <= B + 1	Increment 'B'	
0101	y <= B - 1	Decrement 'B'	
0110	y <= A + B	Add 'A' and 'B'	
0111	y <= A - B	Subtract 'B' from 'A'	
1000	y <= not A	Complement 'A'	Logic
1001	y <= not B	Complement 'B'	
1010	y <= A AND B	AND	
1011	y <= A OR B	OR	
1100	y <= A NAND B	NAND	
1101	y <= A NOR B	NOR	
1110	y <= A XOR B	XOR	
1111	y <= A XNOR B	XNOR	

▪ Algorithmic State Machine (ASM):

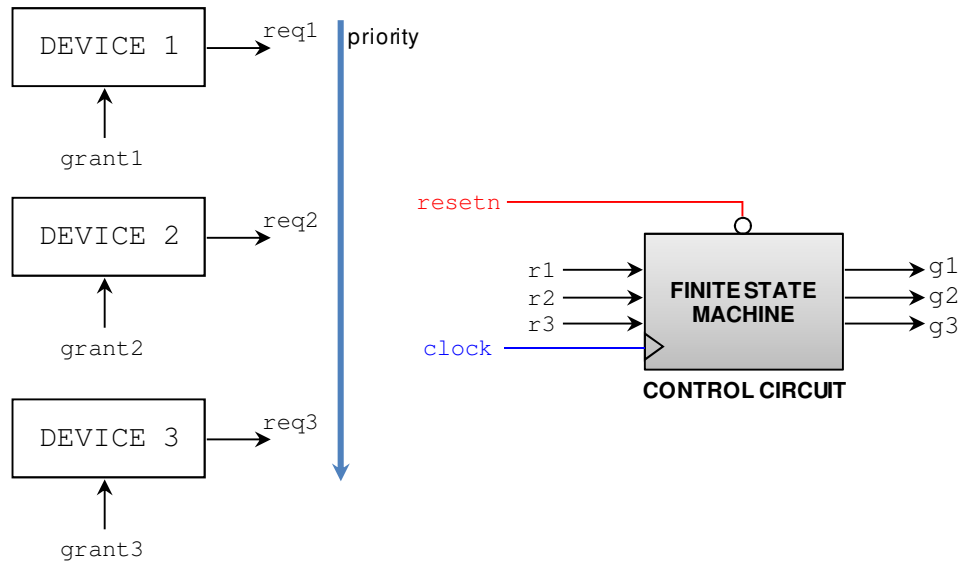




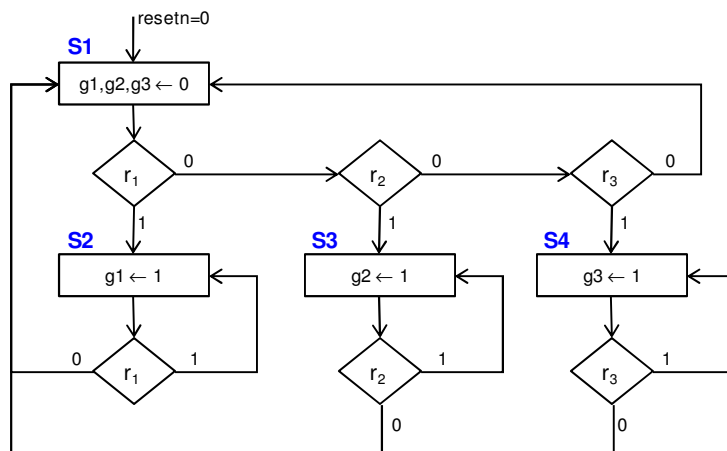
EXAMPLE: ARBITER CIRCUIT

FSM + Datapath circuit:

Three devices can request access to a certain resource at any time (example: access to a bus made of tri-state buffers, only one tri-state buffer can be enabled at a time). The FSM can only grant access to one device at a time. There should be a priority level among devices. If the FSM grants access to one device, one must wait until the request signal to that device is deasserted (i.e. set to zero) before granting access to a different device.

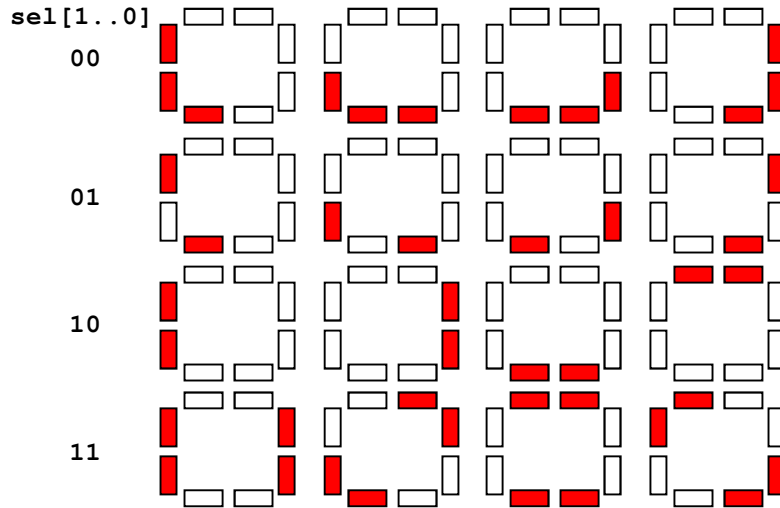
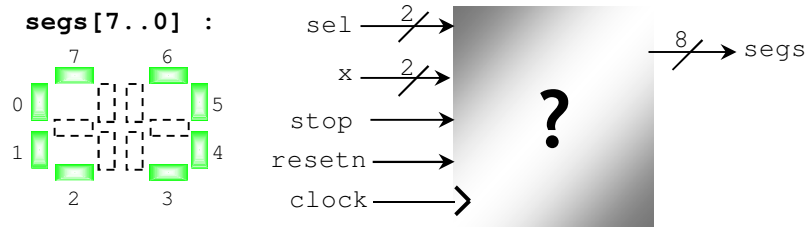


Algorithmic State Machine (ASM) chart:

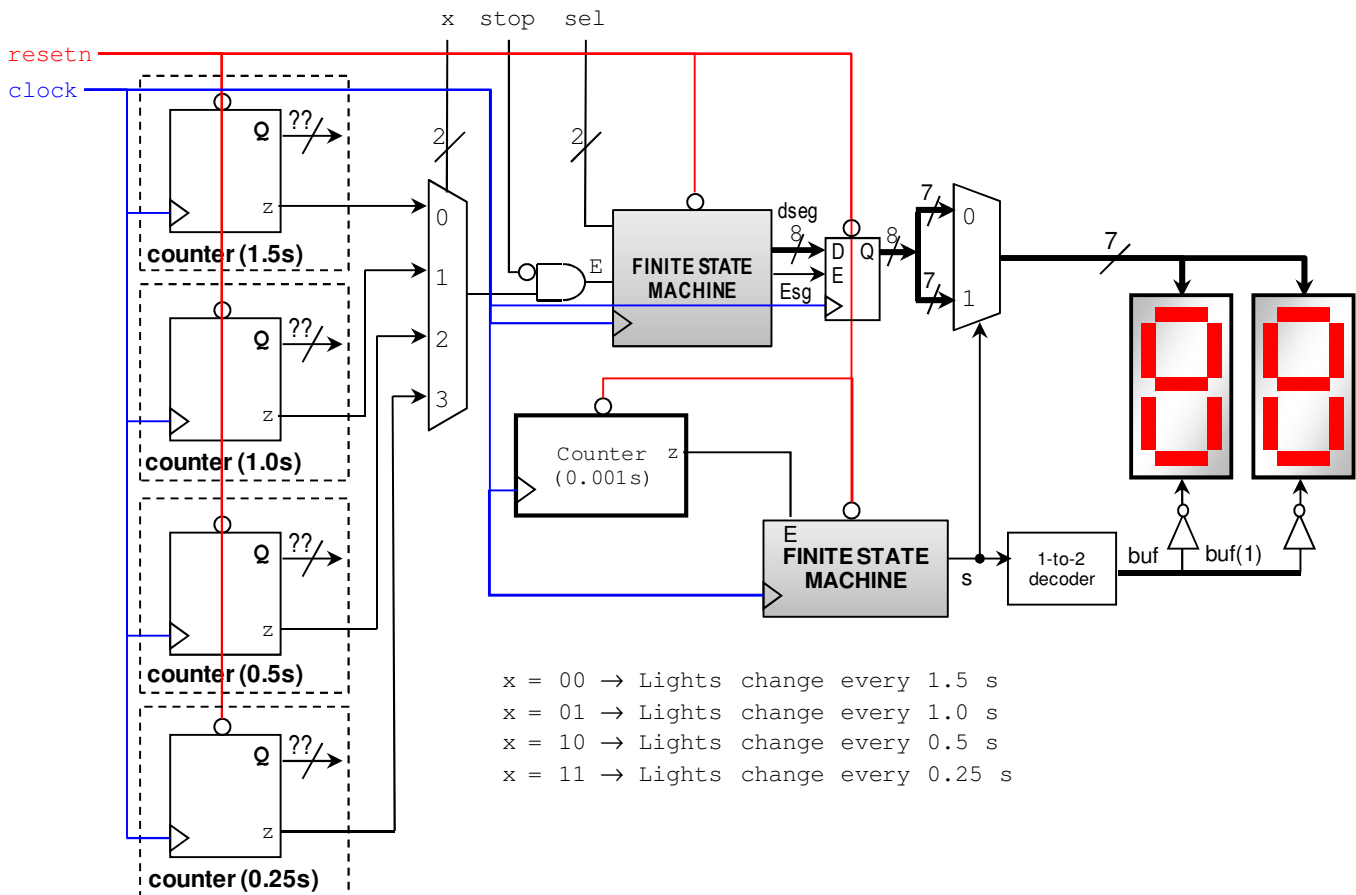


### EXAMPLE: DISPLAYING PATTERNS ON 7-SEGMENT DISPLAYS

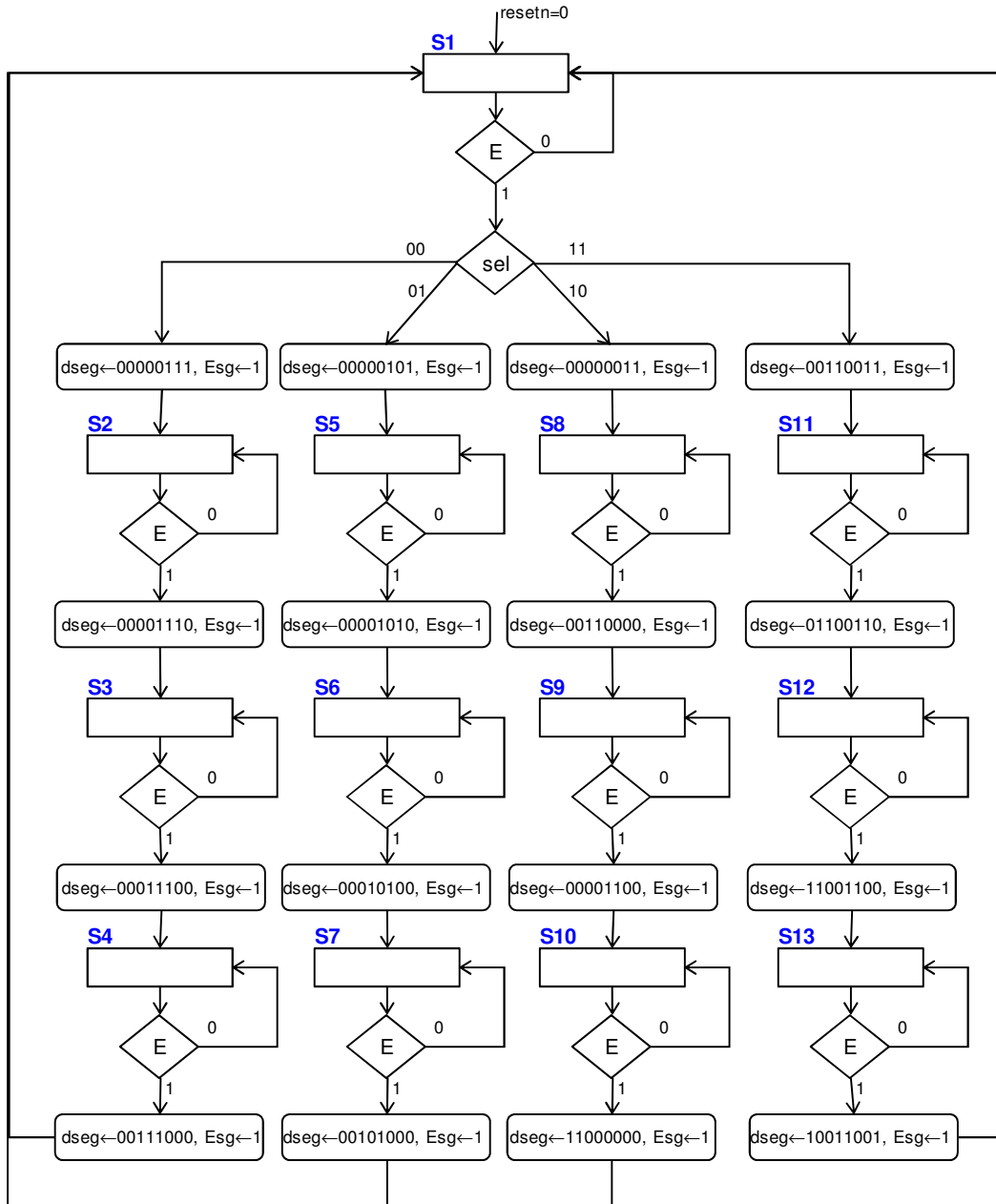
- Different patterns are shown based on the selector 'sel' signal. Two 7-segment displays are used.
- 'stop' input: If it is asserted (stop = 1), the lights' pattern freezes.
- The input 'x' selects the rate of change (every 1.5, 1.0, 0.5, or 0.25 seconds).



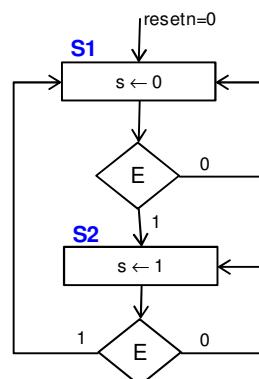
- **FSM + Datapath circuit:**



- Algorithmic State Machine (ASM) chart:



- Algorithmic State Machine (ASM) chart: This is the FSM that controls the output MUX



### EXAMPLE: SERIAL MULTIPLIER

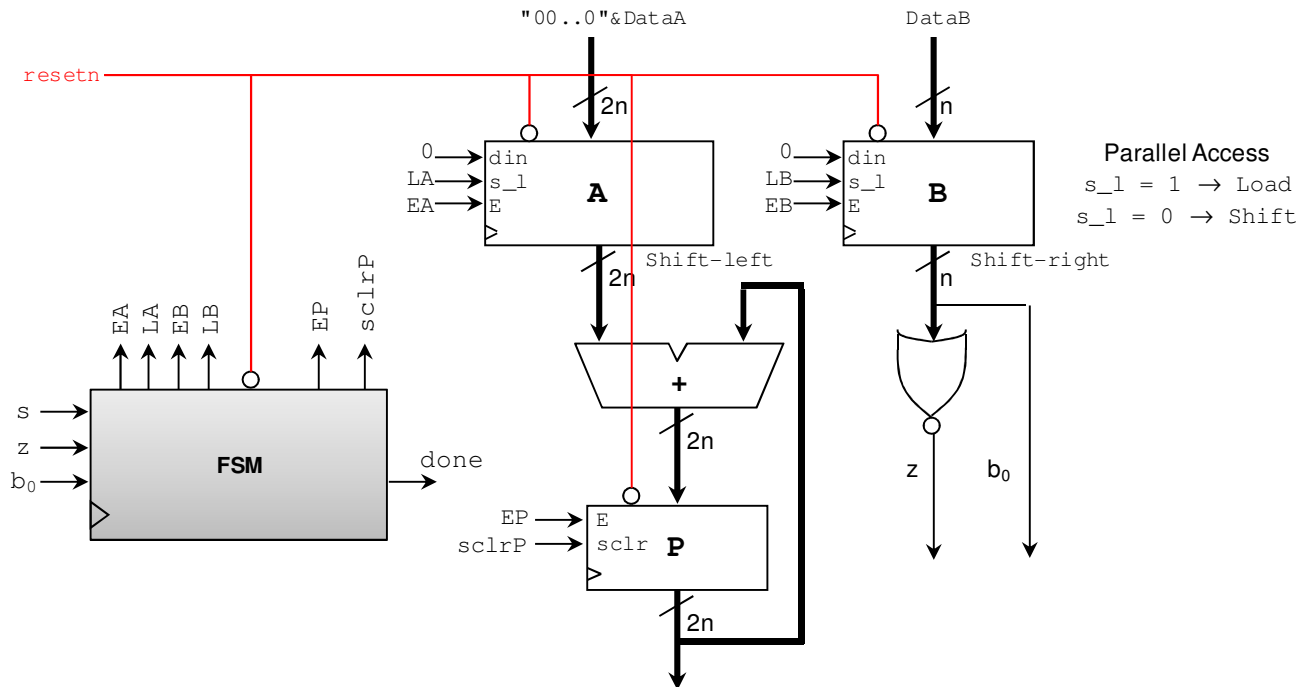
▪ **Sequential Algorithm:**

```

P ← 0, Load A,B
while B ≠ 0
  if b0 = 1 then
    P ← P + A
  end if
  left shift A
  right shift B
end while
    
```

▪ **FSM + Datapath circuit:** Note that this algorithm can also be run on a simple processor. Here, we use dedicated circuitry.

sclr: Synchronous clear. In this case, if sclr = '1' and E = '1', the register contents are initialized to 0.



▪ **Algorithmic State Machine (ASM) chart:**

